

# Riemannian Flow Matching for Brain Connectivity Matrices via Pullback Geometry

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Code:



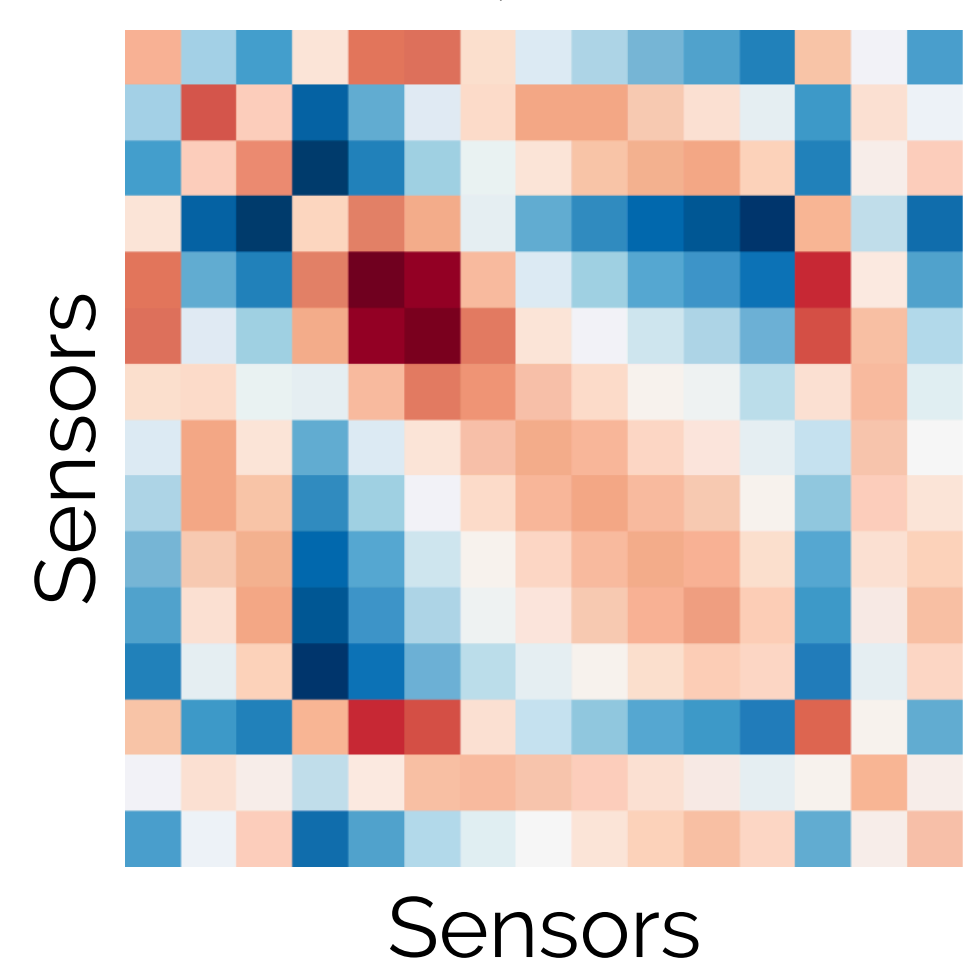
## Brain Connectivity & Manifolds

Modern neuroimaging analyzes signals via connectivity matrices:

### EEG Spatial Covariance

Symmetric Positive Definite (SPD) matrix

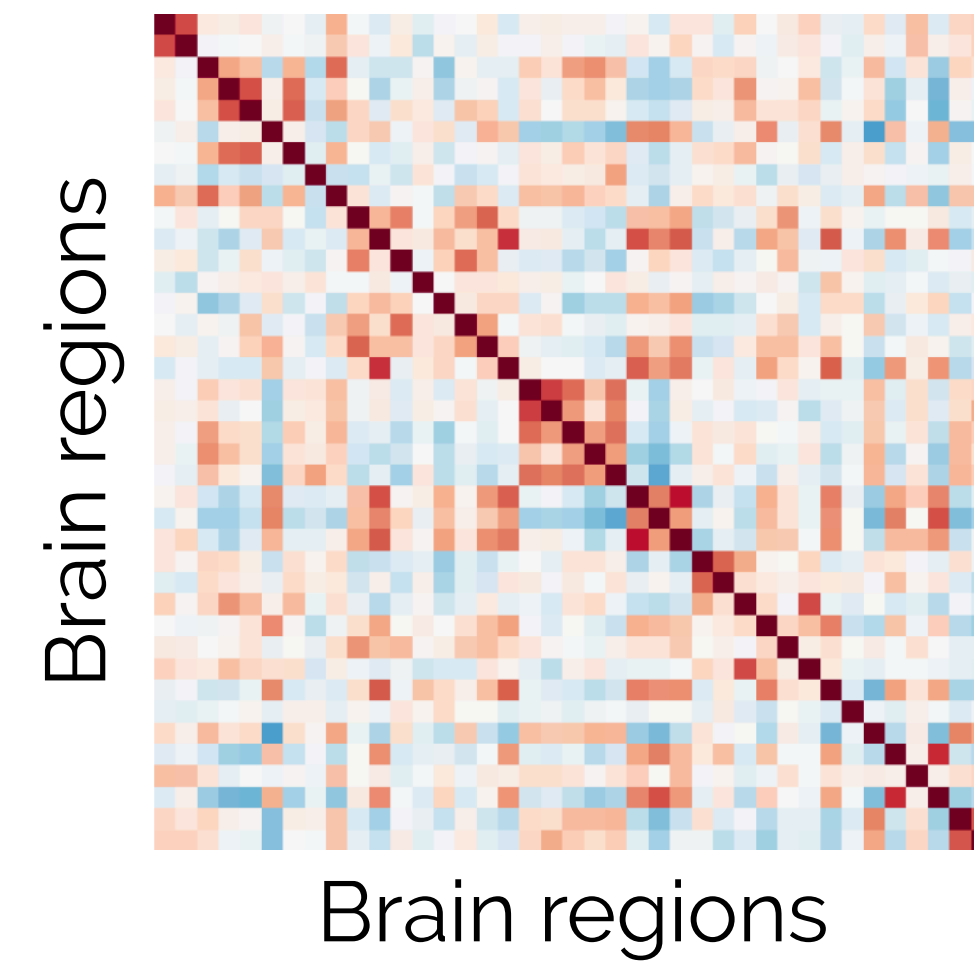
$$\mathbb{S}_d^{++} = \{\Sigma \in \mathbb{R}^{d \times d} \mid \Sigma^\top = \Sigma, \Sigma \succ 0\}$$



### fMRI Functional Connectivity

Correlation matrix

$$\text{Corr}_d = \{\Sigma \in \mathbb{S}_d^{++} \mid \text{diag}(\Sigma) = \mathbf{1}\}$$



Challenges of brain connectivity generation:

1. **Euclidean methods** (e.g., standard Flow Matching) generate non-SPD matrices.
2. **Riemannian methods** require expensive geodesics and Riemannian norms, making training slow (10× slower).

### Contribution:

We propose **DiffGeoCFM** that enables **Euclidean** Flow Matching on matrix manifolds with **pullback metrics** induced by global diffeomorphisms.

- **Fast:** Train and sample in Euclidean space.
- **Exact:** Equivalent to Riemannian Flow Matching on the pullback manifold.
- **Valid:** Guarantees manifold constraints by construction.

## Riemannian Flow Matching

Learn a vector field  $u_\theta^M$  on the manifold  $\mathcal{M}$  to match geodesic velocities [1].

**Training:** Requires computing geodesics  $\gamma(t)$  and Riemannian norms  $\|\cdot\|_{\gamma(t)}$ :

$$\mathcal{L}(\theta) \triangleq \mathbb{E}_{t, x_0, x_1} \left\| u_\theta^M(t, \gamma(t)) - \dot{\gamma}(t) \right\|_{\gamma(t)}^2$$

**Sampling:** Requires solving Riemannian ODEs on  $\mathcal{M}$

$$\dot{x}(t) = u_\theta^M(t, x(t)), \quad x(0) = x_0$$

## Pullback Manifold

$\phi : \mathcal{M} \rightarrow E$  a **global diffeomorphism** to a Euclidean space  $E$ ,

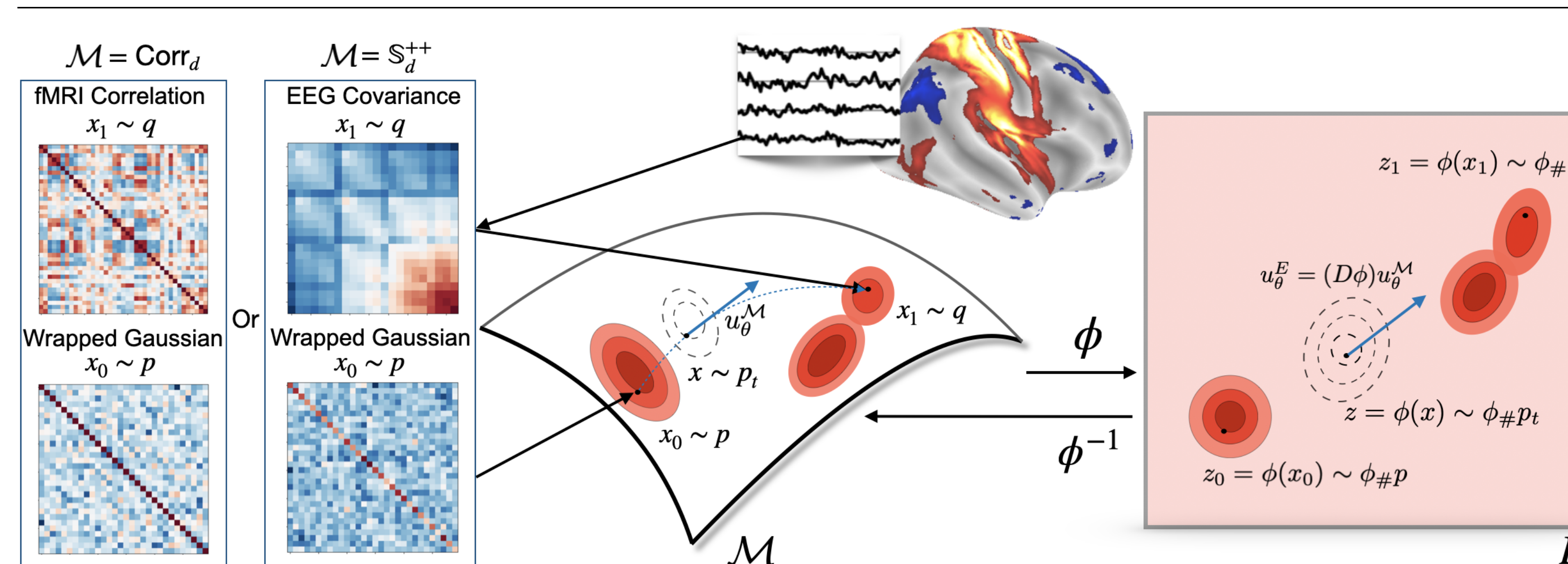
$$g_x(\xi, \eta) \triangleq \langle D\phi(x)[\xi], D\phi(x)[\eta] \rangle, \quad \xi, \eta \in T_x \mathcal{M}$$

**Key Insight:** we can compute everything in  $E$  and map back to  $\mathcal{M}$  via  $\phi$ :

(Geodesic)  $\gamma(t) = \phi^{-1}((1-t)\phi(x_0) + t\phi(x_1))$

(Distance)  $d_M(x_0, x_1) = \|\phi(x_0) - \phi(x_1)\|_E$

## DiffGeoCFM: Overview



**Assumption:** There exists a global diffeomorphism  $\phi : \mathcal{M} \rightarrow E$  to a Euclidean space  $E$ .

- **Training:** Map data to  $E$  via  $\phi$  and learn a Euclidean vector field  $u_\theta^E$  to match straight-line velocities.
- **Sampling:** Solve Euclidean ODE  $\dot{z}(t) = u_\theta^E(t, z)$  in  $E$  and map back to  $\mathcal{M}$  via  $\phi^{-1}$ .

## Theoretical Guarantees

We prove that training in Euclidean space is **exactly equivalent** to Riemannian Flow Matching on  $(\mathcal{M}, g)$  by defining the pulled-back vector field:

$$u_\theta^E(t, z) \triangleq D\phi(\phi^{-1}(z)) \left[ u_\theta^M(t, \phi^{-1}(z)) \right]$$

**Proposition 1 (Training Equivalence):** The Riemannian loss simplifies to the standard Euclidean Flow Matching loss on transformed data  $z = \phi(x)$ :

$$\mathcal{L}(\theta) = \mathbb{E}_{t, z_0, z_1} \underbrace{\left\| u_\theta^E(t, (1-t)z_0 + tz_1) - (z_1 - z_0) \right\|_E^2}_{\text{Standard Euclidean Flow Matching Loss}}$$

**Proposition 2 (Sampling Equivalence):** Let  $z(t)$  be the solution to  $\dot{z}(t) = u_\theta^E(t, z)$  in  $E$ . Then

$$x(t) = \phi^{-1}(z(t))$$

is the exact solution to the Riemannian ODE on  $\mathcal{M}$ .

→ We **avoid all manifold-specific operations (Exp, Log, Parallel Transport) during training and sampling** while being exactly equivalent to Riemannian Flow Matching on  $(\mathcal{M}, g)$ .

## Diffeomorphisms for covariance and correlation matrices

We use specific global diffeomorphisms for neuroimaging data:

- **Covariance ( $\mathbb{S}_d^{++}$ ):** Log-Euclidean map  $\phi_{\mathbb{S}_d^{++}} : \mathbb{S}_d^{++} \rightarrow \mathbb{R}^{d(d+1)/2}$ ,

$$\phi_{\mathbb{S}_d^{++}}(\Sigma) = \text{vec}(\log(\Sigma))$$

- **Correlation ( $\text{Corr}_d$ ):** Normalized Cholesky map  $\phi_{\text{Corr}_d} : \text{Corr}_d \rightarrow \mathbb{R}^{d(d-1)/2}$ ,

$$\phi_{\text{Corr}_d}(\Sigma) = \text{vec}(\text{NormChol}(\Sigma))$$

## Experiments

### Datasets:

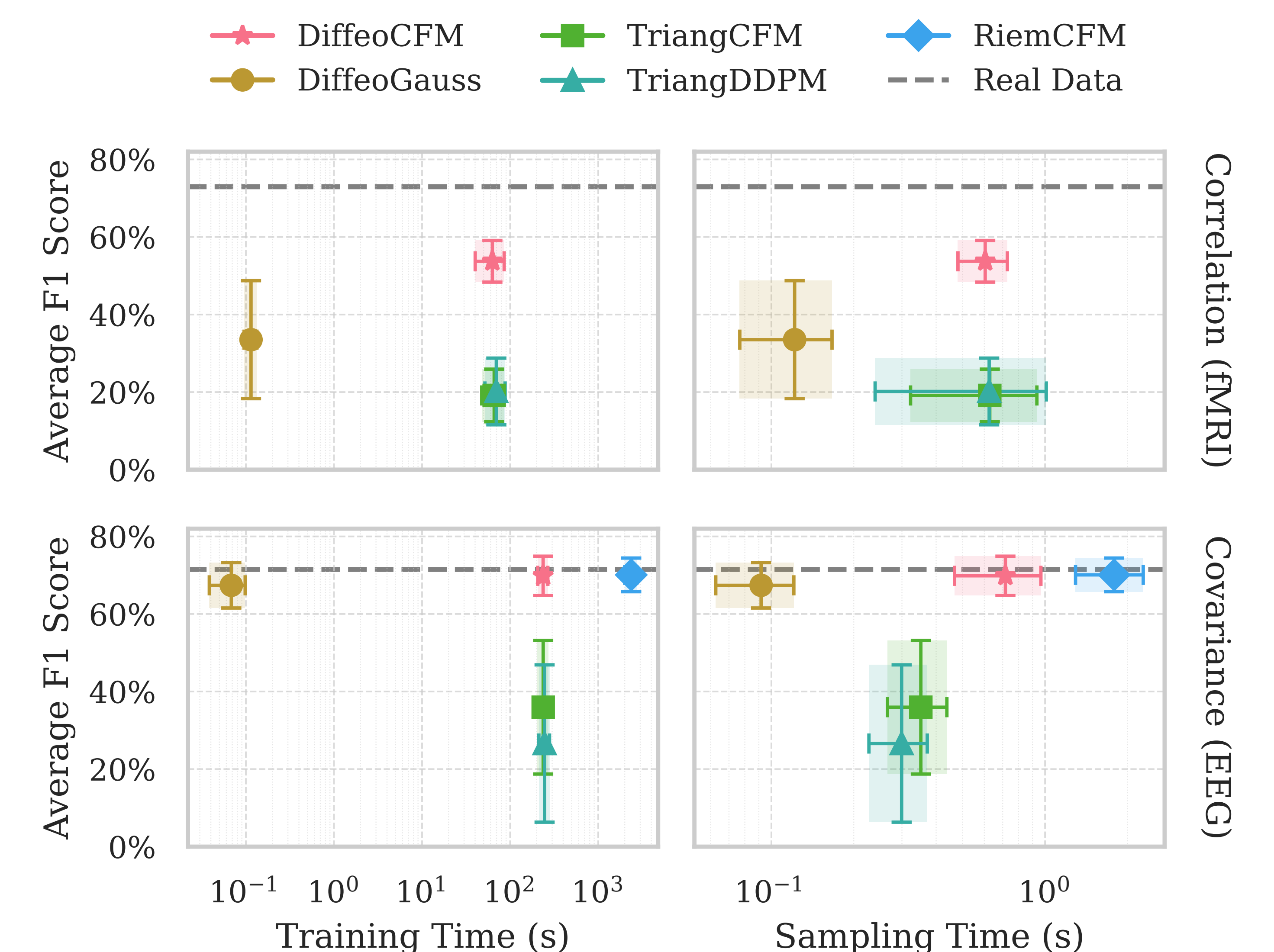
- fMRI (correlation): ABIDE, ADNI, OASIS-3, 4600 scans from 2800 subjects with disease labels (Autism, Alzheimer's, Control) and 10 subject-level splits.
- EEG (covariance): BNCI2014, BNCI2015, > 30k trials from 26 subjects with right hand vs. feet motor imagery labels and cross-session splits.

### Baselines:

- DiffGeoGauss: one Gaussian per class in  $E$  with  $\phi$  [2].
- TriangDDPM / TriangCFM: generates triangular part with DDPM or FM + projection  $\Sigma \leftarrow (1-\alpha)\Sigma + \alpha\mathbf{I}$ .
- RiemCFM: Riemannian Flow Matching (affine-invariant metric) [1].

### Evaluation Metrics:

- Distribution Quality:  $\alpha$ -Precision (fidelity) &  $\beta$ -Recall (diversity) [3].
- Utility (CAS): train a classifier on *generated* data → test on *real* data [4].
- Efficiency: training and sampling time.



## References

- [1] Ricky TQ Chen and Yaron Lipman. "Flow matching on general geometries". In: *The Twelfth International Conference on Learning Representations*. 2024.
- [2] Thibault de Surré et al. "Wrapped Gaussian on the manifold of Symmetric Positive Definite Matrices". In: *Forty-second International Conference on Machine Learning*. 2025.
- [3] Ahmed Alaa et al. "How faithful is your synthetic data? sample-level metrics for evaluating and auditing generative models". In: *International Conference on Machine Learning*. PMLR. 2022, pp. 290–306.
- [4] Suman Ravuri and Oriol Vinyals. "Classification accuracy score for conditional generative models". In: *Advances in neural information processing systems* 32 (2019).