ON THE USE OF GEODESIC TRIANGLES BETWEEN GAUSSIAN DISTRIBUTIONS FOR CLASSIFICATION PROBLEMS

Time series for remote sensing and classification

In recent years, many image time series have been taken from the **earth** with different technologies: SAR, multi/hyper spectral imaging, ...

Objectives: segment semantically these data using spatial information, temporal information and **sensor diversity** (spectral bands, polarization...).



Figure 1. Multivariate image time series.

Applications: disaster assessment, activity monitoring, land cover mapping, crop type mapping, ...

Classification pipeline



Figure 2. Classification pipeline.

Examples of θ : $\theta = \Sigma$ a covariance matrix, $\theta = (\mu, \Sigma)$ a vector and a covariance matrix,

Existing work and Riemannian geometry

 $m{x}_1,\cdots,m{x}_n\in\mathbb{R}^p$ realizations of $m{x}\sim\mathcal{N}(m{0},m{\Sigma}),\,m{\Sigma}\in\mathcal{S}_p^{++}$ (set of p imes p symmetric definite matrices).

Step 2: maximum likelihood estimator:

$$\hat{\boldsymbol{\Sigma}} = rac{1}{n} \sum_{i=1}^{n} \boldsymbol{x}_i \boldsymbol{x}_i^T.$$

Step 3: Riemannian manifold of centered Gaussian distributions: \mathcal{S}_p^{++} with the Fisher information metric: $orall m{\xi}_{m{\Sigma}}, m{\eta}_{m{\Sigma}}$ in the tangent space at $m{\Sigma}$

$$\langle \boldsymbol{\xi}_{\boldsymbol{\Sigma}}, \boldsymbol{\eta}_{\boldsymbol{\Sigma}}
angle_{\boldsymbol{\Sigma}}^{\mathsf{FIM}} = \mathrm{Tr} \left(\boldsymbol{\Sigma}^{-1} \boldsymbol{\xi}_{\boldsymbol{\Sigma}} \boldsymbol{\Sigma}^{-1} \boldsymbol{\eta}_{\boldsymbol{\Sigma}}
ight).$$

Riemannian distance

$$d_{\mathcal{S}_{p}^{++}}(\boldsymbol{\Sigma}_{l},\boldsymbol{\Sigma}_{m}) = \left\| \log \left(\boldsymbol{\Sigma}_{l}^{-\frac{1}{2}} \boldsymbol{\Sigma}_{m} \boldsymbol{\Sigma}_{l}^{-\frac{1}{2}} \right) \right\|_{2}$$

• Riemannian center of mass of a set $\{\Sigma_i\}$

$$\Sigma_{\mathsf{mean}} = \operatorname*{arg\,min}_{\mathbf{\Sigma}\in\mathcal{S}_p^{++}} \sum_i d^2_{\mathcal{S}_p^{++}}(\mathbf{\Sigma},\mathbf{\Sigma}_i).$$

For a full description of the manifold S_p^{++} and its associated center of mass: see [1, 2].

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The Riemannian manifold of non-centered Gaussian distributions

 $\mathbb{R}^p imes \mathcal{S}_p^{++}$ with the Fisher information metric: $\forall \xi = \left(\boldsymbol{\xi}_{\mu}, \boldsymbol{\xi} \right)$ space

$$\langle \boldsymbol{\xi}, \boldsymbol{\eta} \rangle_{(\boldsymbol{\mu}, \boldsymbol{\Sigma})}^{\mathsf{FIM}} = \boldsymbol{\xi}_{\boldsymbol{\mu}}^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\eta}_{\boldsymbol{\mu}} + \frac{1}{2} \operatorname{Tr} \left(\boldsymbol{\Sigma}^{-1} \boldsymbol{\xi}_{\boldsymbol{\Sigma}} \boldsymbol{\Sigma}^{-1} \boldsymbol{\eta}_{\boldsymbol{\Sigma}} \right).$$

Problem: this Riemannian geometry is not fully known... (see [3, 4])



Figure 3. The geodesic between two non-centered Gaussian distributions is unknown in general.

Geodesic triangles for classification problems



Figure 4. A geodesic triangle.

Divergence δ : arc length of the path between $(\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1)$ and $(\boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2)$.

 $\delta_c: \quad (\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1) \to (\boldsymbol{\mu}_1, c\boldsymbol{\Sigma}_1) \to (\boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2),$ $\delta_{\perp}: (\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1) \to (\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1 + \Delta \boldsymbol{\mu} \Delta \boldsymbol{\mu}^T) \to (\boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2),$

Center of mass and Riemannian optimization

	Riemannian center of mass $(oldsymbol{\mu}_{mean}, oldsymbol{\Sigma}_{mean})$ of a set $\{(oldsymbol{\mu}_i, oldsymbol{\Sigma}_i)\}$				
	$(\boldsymbol{\mu}_{\text{mean}}, \boldsymbol{\Sigma}_{\text{mean}}) = \argmin_{(\boldsymbol{\mu}, \boldsymbol{\Sigma}) \in \mathbb{R}^p \times \mathcal{S}_p^{++}} \sum_i \delta^2 \left(\left(\boldsymbol{\mu}, \boldsymbol{\Sigma} \right), \left(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i \right) \right)$	(6)			
c positive	Algorithm to minimize a real-valued function f defined on $\mathbb{R}^p imes \mathcal{S}_p^{++}$:				
(1)	Input : Initial iterate (μ_1, Σ_1) . Output: Sequence of iterates $\{(\mu_k, \Sigma_k)\}$. k := 1;				
	while no convergence do Compute a step size α and set $(\boldsymbol{\mu}_{k+1}, \boldsymbol{\Sigma}_{k+1}) := R_{(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}(-\alpha \operatorname{grad} f(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k));$ k := k + 1;				
(2)	end Algorithm 1: Riemannian gradient descent				
(3)	 grad f(μ_k, Σ_k) is the Riemannian gradient of f at (μ_k, Σ_k) computed in Proposition 1, R_(μ_k,Σ_k) is a second order retraction at (μ_k, Σ_k) derived in Proposition 2. 				
(4)	For a detailed introduction to optimization on Riemannian manifolds: see [5].				

$$oldsymbol{\xi}_{oldsymbol{\Sigma}}ig),\eta=\left(oldsymbol{\eta}_{oldsymbol{\mu}},oldsymbol{\eta}_{oldsymbol{\Sigma}}ig)$$
 in the tangent

(5)

$$\mathcal{N}(\boldsymbol{\mu}_2,\boldsymbol{\Sigma}_2)$$

$$\mathcal{N}(\boldsymbol{\mu}_2,\boldsymbol{\Sigma}_2)$$

 $\forall c > 0$ $\Delta oldsymbol{\mu} = oldsymbol{\mu}_2 - oldsymbol{\mu}_1$

$$(\mathbf{x}_{k})(-\alpha \operatorname{grad} f(\boldsymbol{\mu}_{k}, \boldsymbol{\Sigma}_{k}));$$

Breizhcrops dataset [6]:

- satellite,
- meadows and temporary meadows,
- 13 spectral bands.



Estimator	Geometry	Overall accuracy (%)	Average accuracy (%)
$oldsymbol{X}_j$	$\mathbb{R}^{p imes n}$	10.1	18.5
Mean $\hat{oldsymbol{\mu}}_j$	\mathbb{R}^p	13.2	14.8
Covariance matrix $\hat{\mathbf{\Sigma}}_j$	\mathcal{S}_p^{++}	43.9	28.1
Centered covariance matrix $\hat{\mathbf{\Sigma}}_j$	\mathcal{S}_p^{++}	46.7	30.1
Proposed - $(\hat{oldsymbol{\mu}}_j, \hat{oldsymbol{\Sigma}}_j)$	δ_c	54.3	37.0
Proposed - $(\hat{\mu}_j, \hat{\Sigma}_j)$	δ_{\perp}	53.3	35.7

Table 1. Accuracies of Nearest centroïd classifiers on the Breizhcrops dataset.

estimators/geometries are considered:

- X_j : raw time-series with the Euclidean distance $d(X_l, X_m) = ||X_l X_m||_F$ and the arithmetic mean $\boldsymbol{X}_{\text{mean}} = \frac{1}{M} \sum_{j=1}^{M} \boldsymbol{X}_{j},$
- $\hat{\mu}_j = \frac{1}{n} \sum_{i=1}^n [X_j]_{:,i}$: temporal mean with the Euclidean distance $d(\hat{\hat{\mu}}_l, \hat{\hat{\mu}}_m) = \|\hat{\mu}_l - \hat{\mu}_m\|_2$ and the arithmetic mean $\hat{\mu}_{mean} = \frac{1}{M} \sum_{j=1}^M \hat{\mu}_j$,
- associated Riemannian mean (4),
- the distance (3) and its associated Riemannian mean (4),
- its associated Riemannian center of mass (6),
- its associated Riemannian center of mass (6).

Application

• more than 600 000 crop time series across the whole Brittany taken by the Sentinel-2

• 9 classes: barley, wheat, rapeseed, corn, sunflower, orchards, nuts, permanent

Figure 5. Reflectances of a Sentinel-2 time series from the Breizhcrops dataset.

We denote the columns of a time-series by $X_j = [[X_j]_{:,1}, \cdots, [X_j]_{:,n}] \in \mathbb{R}^{p \times n}$. Different

• $\hat{\Sigma}_j = \frac{1}{n} \sum_{i=1}^n [X_j]_{:,i} [X_j]_{:,i}^T$: temporal covariance matrix with the distance (3) and its

• $\hat{\Sigma}_j = \frac{1}{n} \sum_{i=1}^n \left([X_j]_{:,i} - \hat{\mu}_j \right) \left([X_j]_{:,i} - \hat{\mu}_j \right)^T$: temporal centered covariance matrix with

• $(\hat{\mu}_i, \hat{\Sigma}_j)$: temporal mean and centered covariance matrix with the divergence δ_c and

• $(\hat{\mu}_j, \hat{\Sigma}_j)$: temporal mean and centered covariance matrix with the divergence δ_\perp and

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